

Neural Networks for Control

Neural Networks for Control brings together examples of all the most important paradigms for the application of neural networks to robotics and control. Primarily concerned with engineering problems and approaches to their solution through neurocomputing systems, the book is divided into three sections: general principles, motion control, and applications domains (with evaluations of the possible applications by experts in the applications areas.) Special emphasis is placed on designs based on optimization or reinforcement, which will become increasingly important as researchers address more complex engineering challenges or real biological-control problems. A Bradford Book. Neural Network Modeling and Connectionism series



12,00 €

11,21 € (zzgl. MwSt.)

Nicht mehr lieferbar

Artikelnummer: 9780262631617

Medium: Buch

ISBN: 978-0-262-63161-7

Verlag: MIT Press Ltd

Erscheinungstermin: 02.03.1995

Sprache(n): Englisch

Auflage: Neuauflage 1995

Serie: Neural Network Modeling and Connectionism

Produktform: Kartoniert

Gewicht: 862 g

Seiten: 544

Format (B x H): 152 x 229 mm

