

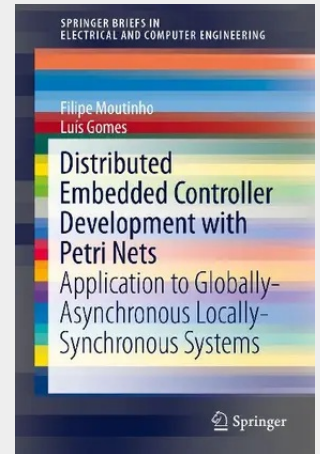
Distributed Embedded Controller Development with Petri Nets

Application to Globally-Asynchronous Locally-Synchronous Systems

This book describes a model-based development approach for globally-asynchronous locally-synchronous distributed embedded controllers. This approach uses Petri nets as modeling formalism to create platform and network independent models supporting the use of design automation tools. To support this development approach, the Petri nets class in use is extended with time-domains and asynchronous-channels. The authors' approach uses models not only providing a better understanding of the distributed controller and improving the communication among the stakeholders, but also to be ready to support the entire lifecycle, including the simulation, the verification (using model-checking tools), the implementation (relying on automatic code generators), and the deployment of the distributed controller into specific platforms.

- Uses a graphical and intuitive modeling formalism supported by design automation tools;
- Enables verification, ensuring that the distributed controller was correctly specified;
- Provides flexibility in the implementation and maintenance phases to achieve desired constraints (high performance, low power consumption, reduced costs), enabling porting to different platforms using different communication nodes, without changing the underlying behavioral model.

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53,49 €

49,99 € (zzgl. MwSt.)

Lieferfrist: bis zu 10 Tage

Artikelnummer: 9783319208213

Medium: Buch

ISBN: 978-3-319-20821-3

Verlag: Palgrave Macmillan

Erscheinungstermin: 22.10.2015

Sprache(n): Englisch

Auflage: 1. Auflage 2016

Serie: SpringerBriefs in Electrical and Computer Engineering

Produktform: Kartoniert

Gewicht: 1533 g

Seiten: 79

Format (B x H): 155 x 235 mm

