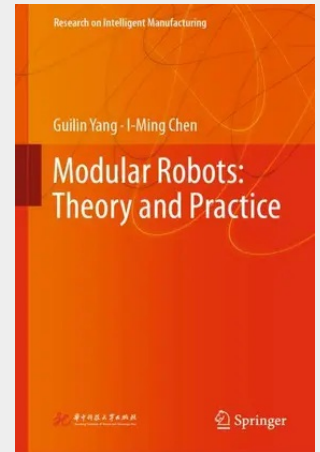


Modular Robots: Theory and Practice

This book introduces the latest advances in modular robotics, and presents a unified geometric framework for modeling, analysis, and design of modular robots, including kinematics, dynamics, calibration, and configuration optimization. Supplementing the main content with a wealth of illustrations, the book offers a valuable guide for researchers, engineers and graduate students in the fields of mechatronics, robotics, and automation who wish to learn about the theory and practice of modular robots.

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